

## CD Automation S.r.I.

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## CD3000M-1PH Thyristor Unit up to 110A

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Thyristor units are used in power industrial equipment. When the thyristor unit is working, there are on the unit the following voltages

- Maximum main supply voltage on power terminals up to 600V.
- Auxiliary supply 230-460Vac.
- Fan voltage $230 \mathrm{Vac} 50 / 60 \mathrm{~Hz}$ Power consumption 14W.

Don't remove the plastic cover which provides adequate protection against electric shock.
Don't use this thyristor in aerospace and nuclear application.

## Electric Shock Hazard (Risque the choque électrique)

When thyristor unit has been connected to main supply voltage and is switched off, before to touch it be secure that the unit is isolated and wait at least one minute to permit to discharge internal capacitors. Thus be secure that:

- access to thyristor unit is only permitted to specialized personnel;
- the authorised personnel must read this manual before to have access to the unit;
- the access to the units must be denied to unauthorized personnel.


## I mportant warnings(attention)

- Local regulations regarding electrical installation should be rigidly observed.
- Safety regulations must be rigidly observed.
- Don't bend components to maintain insulation distances.
- Protect the units from high temperature, humidity and vibrations.
- Don't touch components to prevent elettrostatichal discharges on them.
- Verify that all ratings are in line with real needs.
- If authorized personnel must measure voltage, current etc. on units, take away rings and other jewels from fingers and hands.
- Authorized personnel working on thyristor unit under power supply voltage must work on insulated board. Be secure that board is not connected to earth.

This listing does not represent a complete enumeration of all necessary safety cautions.

## Protection(protection)

CD3000 thyristor family has a polymeric plastic cover in compliance to International specification IP20. To understand if IP20 protection is sufficient should be evaluated the installation place where the units are installed.
Open Type Equipment(équipment de type ouvert).
Maximum surrounding air temperature $40^{\circ} \mathrm{C}$ (Temperature de l'air environnante maximum $40^{\circ} \mathrm{C}$ ).

## Earth(terre)

CD3000 family has isolated heatsink. For safety connect the heatsink to earth to avoid shocks in case that circuit board or thyristors lost insulation. Earth impedance should be correspondent to local earth regulation. Periodically the earth efficiency should be inspected.

## Electronic Supply(alimentation électronique)

CD3000 family electronic circuit should be supplied by dedicated voltage supply for all electronic circuit but not in parallel with contactor's coil, solenoids and other inductive or capacitive loads. It's recommended to use a shielded transformer.

## Electromagnetic compatibility (compatibilité électromagnétique)

Our thyristor unit has an excellent immunity to electromagnetic interferences if all suggestions contained in this manual are respected. In respect to a good Engineering practise, all inductive loads like solenoids contactor coils should have a filter in parallel.

## Emissions (emission)

All thyristor switching at high speed generate some radiofrequency disturbance. CD3000 serie complies with EMC rules for CE mark. In many installations near electronic devices has not been noted problems. If radiofrequency device at low frequency are used near the thyristor unit, some precautions should be taken like line filters and shielded cables for input signal and for load cables.


We reserves the right to apply modifications to the our products without any advice.

## 1. Glossary



### 1.1 Terminology

V: voltage power supply.
I: the full circulating current in thyristor unit.
P: total load power.

### 1.2 Input signal

SSR: This input type is a square waveform generated by a temperature controller.
AN: Analog input.
IRS: Communication command.

### 1.3 Power feed back

Feedback: supply voltage fluctuation changes the power to the load. To overcome this effect the voltage supplied to the load is measured and compared with power demand from controller, the error signal is used to automatically hold the power at demanded level.

### 1.4 What is a thyristor unit

A thyristor unit is semiconductor device which acts as a switch formed by two thyristors in antiparallel. To switch on the alternating current the input signal will be on and the thyristor will switch off at first zero crossing voltage with no input signal. The benefits of thyristor units compared with elettromechanical contactors are numerouses: no mooving parts, no maintenance and capacity to switch very fast. Thyristors are the only solution to control transformers and special loads that change resistance with temperature and with age.


## 2. Technical specifications

### 2.1 General features

| Operating temperature | $0 \div 40^{\circ} \mathrm{C}$ for higher temperature see derating curve |
| :---: | :---: |
| Voltage power supply | 24 V minimum, 480 V max and 600 V on request |
| I nput signal | $\begin{aligned} & \text { SSR } \\ & 4 \div 20 \mathrm{~mA} \\ & 0 \div 10 \mathrm{~V} \\ & \text { potentiometer ( } 10 \mathrm{k} \text { ohm) } \\ & \text { customer configurable with automatic zero/span calibration } \end{aligned}$ |
| Firing mode | One of these firing modes can be configured on line via serial port Zero Crossing (ZC) <br> Single Cycle (SC) <br> Burst Firing (BF) <br> Soft Start + Burst Firing (S + BF) <br> Delayed Triggering + Burst Firing (DT + BF) <br> Phase Angle (PA) |
| Auxiliary voltage supply | $\begin{aligned} & 230 \mathrm{~V} \text { range }(230 \pm 15 \%) \quad \text { 10VA } \\ & 460 \mathrm{~V} \text { range }(380-15 \%) \div(460+15 \%) ; \text { 10VA } \\ & \text { (sincronized with supply Voltage) } \end{aligned}$ |
| Fan voltage supply | $\begin{aligned} & 230 \mathrm{~V} \pm 15 \% ; \\ & 110 \mathrm{~V} \pm 15 \% \text { on request } \end{aligned}$ |
| Heater break alarm | Discrimination better than 20\%. Circuit microprocessor based to diagnose partial or total load failure and short circuit on Thyristors. Latching alarm plus reset. Relay output $0,5 \mathrm{~A}$ at 125 V |
| Line Drop Voltage | Automatic compensation $\pm 15 \%$ of supply voltage with analog input |
| Mounting | Din rail mounting up to 110A |
| Protection | IP20 |

### 2.2 Input features

| Input signal | Maximum current <br> drain | Input <br> Impedance | ON condition | OFF condition |
| :---: | :---: | :---: | :---: | :---: |
| SSR | 5 mA constant current | $\geq 4 \mathrm{~V}-\mathrm{max} 30 \mathrm{~V}$ | $\leq 1 \mathrm{~V}$ |  |
| Analog $0 \div 10 \mathrm{~V}$ | - | 8200 ohm |  |  |
| Analog $4 \div 20 \mathrm{~mA}$ | - | 100 ohm |  |  |
| Potentiometer <br> 10 K ohm |  | 8200 ohm |  |  |

### 2.3 Output features

NA=not Available

| Current | Voltage range | Ripetitive peak reverse voltage |  | Latching current | Max peak one cycle | Leakage current | $I^{2}$ T value thyristor | $\begin{array}{\|c\|} \hline \text { Frequency } \\ \text { range } \end{array}$ | Power loss | I solation Voltage |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| (A) | (V) | (480V) | (600V) | (mAeff) | $\begin{gathered} \text { (10msec.) } \\ \text { (A) } \end{gathered}$ | ( mAeff) | tp $=10 \mathrm{msec}$ | ( Hz ) | $\begin{gathered} \text { I = I nom } \\ \text { (W) } \end{gathered}$ | Vac |
| 15 | $24 \div 480$ | 1200 | 1200 | 150 | 230 | 15 | 610 | $47 \div 70$ | 18 | 2500 |
| 25 | $24 \div 480$ | 1200 | 1200 | 150 | 230 | 15 | 610 | $47 \div 70$ | 30 | 2500 |
| 35 | $24 \div 600$ | 1200 | 1600 | 250 | 400 | 15 | 780 | $47 \div 70$ | 42 | 2500 |
| 45 | $24 \div 600$ | 1200 | 1600 | 250 | 600 | 15 | 1800 | $47 \div 70$ | 54 | 2500 |
| 60 | $24 \div 600$ | 1200 | 1600 | 450 | 1000 | 15 | 4750 | $47 \div 70$ | 72 | 2500 |
| 90 | $24 \div 600$ | 1200 | 1600 | 450 | 2000 | 15 | 19100 | $47 \div 70$ | 108 | 2500 |
| 110 | $24 \div 600$ | 1200 | 1600 | 450 | 1540 | 15 | 11300 | $47 \div 70$ | 137 | 2500 |

### 2.4 Derating curve



## 3. Ordering information

Model CD3000M 1PH

| CD3000M-1PH | $\mathbf{1}$ | $\mathbf{2}$ | $\mathbf{3}$ | $\mathbf{4}$ | $\mathbf{5}$ | $\mathbf{6}$ | $\mathbf{7}$ |
| :--- | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Ex:CD3000M 1PH/ | 90A/ | $\mathbf{4 0 0 V}$ | $\mathbf{l 4 8 0 V}$ | $\mathbf{4 6 0 V}$ | SSR/ | ZC/ | UL |


| $\mathbf{1}$ | Nominal current of CD3000M |  |  |
| :--- | :--- | :--- | :--- | :--- |
| $15 A$ | $45 A$ | 110 A |  |
| 25 A | 60 A |  |  |
| 35 A | 90 A |  |  |

## 2 Operating Load Voltage (incoming voltage supply)

Specify the value of the line supply.

## 3 Max VOLTAGE of CD3000M <br> 480V <br> 600 V

The voltage on the identification label must be equal or more than operating voltage. The minimum voltage supply to the load is 24 V .

| 4 | Auxiliary Voltage |
| :--- | :--- |
| 230 V | $200 \div 230 \mathrm{~V} \pm 15 \% ; 10 \mathrm{VA}$ |
| 460 V | $300 \div 460 \mathrm{~V} \pm 15 \% ;$ 10VA |
| 600 V | $600 \mathrm{~V} \pm 15 \% ; 10 \mathrm{VA}$ (on request) |


| $\mathbf{5}$ | I nput |
| :--- | :--- |
| SSR | $4 \div 30 \mathrm{VDC}$ |
| $0-10 \mathrm{~V}$ | $0 \div 10 \mathrm{~V}$ analog input |
| $4-20 \mathrm{~mA}$ | $4 \div 20 \mathrm{~mA}$ analog input |
| 10 K pot | Potentiometer |


| $\mathbf{6}$ | Firing |  |
| :--- | :--- | :--- |
| ZC | Zero Crossing |  |
| SC | Single Cycle |  |
| BF | Burst firing. Specify the number on ON cycles at 50\% of |  |
| S+BF | power. |  |
| Soft Start + Burst Firing |  |  |
| PA | Phase Angle. Soft Start and feedback in voltage are not |  |
|  | availables, just in supply compensation. If feedback is <br> necessary, you need to use CD3200. |  |
| DT | Delayed Triggering + Burst Firing |  |


| 7 | Options |
| :--- | :--- |
| COMM | MODBUS protocol in RS485 is standard |
| CD-KP | External Keypad |
| HB | Heater Break Alarm |
| FAN110 | Fan voltage supply 110VAC $\pm 15 \%$ (std 230VAC $\pm 15 \%$ ) |
|  | 14W 50/60Hz |
| UL | UL Certification |

## 4. Installation and wiring information

### 4.1 I dentification of the unit



Before to install the CD3000M unit examine for damages or deficiencies. If any is found, notify the carrier immediately. Check that the product features shown on CD3000M cover and identification label corresponds to that ordered.


### 4.2 Installation



CD3000M unit should be always mounted in vertical position to improve air cooling on heatsink. Maintain minimum distances in vertical and in horizontal as below represented. Don't install in proximity of hot elements and near units generating electromagnetic interferences.
When more units are mounted inside a cubicle provide air circulation as below represented.
Sometimes it is necessary to provide a fan to have a better air circulation.


### 4.3 Dimensions



| Size | $\mathbf{W ( m m})$ | $\mathbf{H ( m m})$ | $\mathbf{D}(\mathbf{m m})$ |
| :---: | :---: | :---: | :---: |
| 15A (S0C) | 63 | 120 | 120 |
| $25 A(S 0 C)$ | 63 | 120 | 120 |
| $35 A(S 3 C)$ | 85 | 120 | 120 |
| $45 A(S 3 C)$ | 148 | 120 | 120 |
| 60A (S7C) | 148 | 120 | 159 |
| 90A (S7C) | 148 | 128 | 159 |
| $110 A(S 8 C)$ |  | 159 |  |

### 4.4 CT dimensions (Heater Break HB)



### 4.5 Fixing holes



| Size | A(mm) | B(mm) | C(mm) | D(mm) |
| :---: | :---: | :---: | :---: | :---: |
| 15A (S0C) | 110 | - | - | - |
| 25A (S0C) | 110 | - | - | - |
| 35A (S3C) | - | 110 | - | - |
| 45A (S3C) | - | 110 | - | - |
| 60A (S7C) | - | - | 110 | 65 |
| 90A (S7C) | - | - | 110 | 65 |
| 110A (S8C) | - | - | 110 | 65 |

## 5. Wiring I nstructions



Warning: this procedure can be done just by specialized personnel.

CD3000M unit has isolated heatsink. For safety connect the heatsink to hearth using its terminal with hearth symbol.
CD3000M can be susceptible to airborne interferences from near equipment or from interferences on main supply, so a number of precautions must be taken.

- Contactors coils and chokes must have in parallel a RC filter and must be supplied with a different voltage line.
- All input/output signal must use screened bifilar wires.
- Signal input and output must not routing in same cable try and must not be parallel.
- Local regulations regarding electrical installation should be rigidly observed.


### 5.1.1Auxiliary terminals



Before connect or disconnect, make sure that the power, control cables and wires are insulated from the voltage.

| Terminal |  |
| :---: | :--- |
| 1 | - |$\quad$ External Calibration command 24 Vdc max

### 5.1.2 Power Terminals



Before connect or disconnect, make sure that the power, control cables and wires are insulated from the voltage.

| Terminal |  |
| :---: | :--- |
| L1 | Line Input |
| T1 | Load Output |

### 5.2 Cabling detail

Use $75^{\circ} \mathrm{C}$ copper (CU) conductor only, provided with the terminal type indicated below.
(Utiliser conducteur de cuivre (CU) pour $75^{\circ} \mathrm{C}$ seulement, avec les terminal suivants )
\(\left.$$
\begin{array}{|c|c|c|c|}\hline \text { Current/ courant } & \begin{array}{c}\text { Torque/ couple } \\
\text { Lb-in (N-m) }\end{array} & \text { Wire/ cable } & \begin{array}{c}\text { Wire } \\
\text { terminal/ terminal }\end{array} \\
\hline 15 \mathrm{~A}, 25 \mathrm{~A}, 35 \mathrm{~A}, 45 \mathrm{~A} & 26.6(3.0) & 18-8 & \begin{array}{c}\text { UL Listed (ZMVV) } \\
\text { Wire Pin Terminal } \\
\text { (terminal avec cosse) }\end{array} \\
\hline \text { 60A, 90A, 110A } & 70.8(8.0) & \begin{array}{c}\text { UL Listed (ZMVV) } \\
\text { - Fork/Spade } \\
\text { Terminal } \\
\text { (terminal avec }\end{array}
$$ <br>
cosse a fourche) <br>
- Copper Tube Cr. <br>
Lug <br>
(cosse tubulaire a <br>

plage étroite)\end{array}\right]\)|  |
| :---: |

Power terminals wire details:

| Current | Supply |  | Load |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | Cable |  | Screw | Clable |  | Screw |
|  | $\mathbf{m m}^{\mathbf{2}}$ | AWG |  | $\mathbf{m m}^{\mathbf{2}}$ | AWG |  |
| $15 A$ | 4 | 12 | M5 | 4 | 12 | M5 |
| $25 A$ | 6 | 10 | M5 | 6 | 10 | M5 |
| $35 A$ | 10 | 8 | M5 | 10 | 8 | M5 |
| $45 A$ | 10 | 8 | M5 | 10 | 8 | M5 |
| $60 A$ | 16 | 6 | M6 | 16 | 6 | M6 |
| $90 A$ | 35 | 3 | M6 | 35 | 3 | M6 |
| $110 A$ | 35 | 2 | M6 | 35 | 2 | M6 |

Auxiliary connectors and earth:

| Current | Auxiliary Supply |  | Earth |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | Cable |  |  | Clable |  | Screw |
|  | $\mathbf{m m}^{2}$ | AWG |  | $\mathbf{m m}^{\mathbf{2}}$ | AWG | M |
| $15 A$ | 0,50 | 18 |  | 4 | 12 | M4 |
| $25 A$ | 0,50 | 18 |  | 4 | 12 | M4 |
| $35 A$ | 0,50 | 18 |  | 6 | 10 | M5 |
| $45 A$ | 0,50 | 18 |  | 6 | 10 | M5 |
| $60 A$ | 0,50 | 18 |  | 10 | 8 | M5 |
| $90 A$ | 0,50 | 18 |  | 16 | 6 | M5 |
| $110 A$ | 0,50 | 18 |  |  | M5 |  |

### 5.3 Wiring Connection

### 5.3.1 CD3000 15-25A



> T The user installation must be protect by electromagnetic circuit breaker or by fuse isolator


#### Abstract

** If the Auxiliary Voltage (written on the identification label) is different from Supply Voltage (to the load ), use an external transformer as designated above.


```
*** CT only with HB option.
```


## NOTE: IMPORTANT

To work, terminals 3-4 must be linked.
The auxiliary voltage supply of Drive $M$ unit must be connected as above, and must be syncronized with load voltage power supply (L1, L2).
5.3.2 CD3000 35-45A


* The user installation must be protect by electromagnetic circuit breaker or by fuse isolator
** If the Auxiliary Voltage (written on the identification label) is different from Supply Voltage (to the load ), use an external transformer as designated above.
*** CT only with HB option.


### 5.3.3 CD3000 60-90A



* The user installation must be protect by electromagnetic circuit breaker or by fuse isolator
** If the Auxiliary Voltage (written on the identification label) is different from Supply Voltage (to the load ), use an external transformer as designated above.

```
*** CT only with HB option.
```


## NOTE: IMPORTANT

To work, terminals 3-4 must be linked.
The auxiliary voltage supply of Drive $M$ unit must be connected as above, and must be syncronized with load voltage power supply (L1, L2).

### 5.3.4 CD3000 110A



NOTE: IMPORTANT
To work, terminals 3-4 must be linked.
The auxiliary voltage supply of D r ive $M$ unit must be connected as above, and must be syncronized with load voltage power supply (L1, L2).
Fan voltage supply standard $230 \mathrm{VAC} \pm 15 \% 14 \mathrm{~W} 50 / 60 \mathrm{~Hz}$ or optional110VAC $\pm 15 \%$ 14W 50/60Hz

### 5.4 LED Status Table

| LED | STATUS | DESCRI PTI ON |
| :---: | :---: | :---: |
| PW | 0 | Auxiliary supply is not connect |
|  | $\bullet$ | Auxiliary supply is connect |
| SC | 0 | SCR OK |
|  | $\bullet$ | SCR short circuit |
| HB | 0 | Laod OK |
|  | $\bullet$ | Load Fault |
| ON | 0 | OFF Condition(Load IS NOT Powered) |
|  | $\bullet$ | ON Condition(Load IS Powered) |

$\square$

## 6. Start up

Before to supply the thyristor unit:

- verify that load current equal or less than nominal;

For resistive load
For inductive load

$$
I=\frac{\mathbf{P}_{\mathrm{Tot}}}{\mathbf{V}} \quad I=\frac{\mathbf{P}_{\mathrm{Tot}}}{\mathbf{V} \cos \phi}
$$

- verify that there is no short circuit on load;
- verify that main voltage equal or less than nominal;
- verify that all auxiliary connections are right and syncronized to main voltage!!!;
- Fan voltage equal than nominal (230V std, 120V optional)

After which supply thyristor unit giving the maximum input signal and verify that load current is equal or less than thyristor unit nominal current.


Warning: this procedure can be done just by specialized personnel.


The thyristor unit is delivered configured and tuned in line with customer requirements. If it's necessary to change on site the configuration, procede as below specified.

### 6.1 To remove the board

1 Remove plastic Cover


2 Pull the PCB


### 6.2 Auxiliary supply



Warning: this procedure can be done just by specialized personnel.

To change auxiliary supply voltage sold the correct link-jumper on main PCB


- If the Auxiliary Voltage (written on the identification label) is different from Supply Voltage (to the load ), use an external transformer.
- If load voltage is not included in range of $230 \mathrm{~V} \pm 15 \%$ or $460 \mathrm{~V}+15 \%$ provide an external transformer with primary equal to load voltage and secondary 230 V if your unit is setted to 230V.


### 6.3 Analog input



Warning: this procedure can be done just by specialized personnel.

### 6.3.1 Setting Analog input

To change input type remove plastic cover and configure jumpers as represented below:

| Jumpers Configuration |  |  |  |
| :---: | :---: | :---: | :---: |
|  | FRONT PCB |  |  |
| I nput | J 7 | J 16 | J 17 |
| SSR | A B C | C B A | $\begin{aligned} & \text { C B A } \\ & 1 \quad 1 \end{aligned}$ |
| $0 \div 10 \mathrm{~V}$ | A B C | C B A | $\begin{array}{lll} \text { C B A } \\ \square & 1 \end{array}$ |
| 4 $\div 20 \mathrm{MA}$ | A B C $11 \square$ | C B A | $\begin{array}{ll} \text { C B A } \\ \square & 1 \end{array}$ |



### 6.3.2 Tuning Analog input

Warning: this procedure can be done just by specialized personnel.


### 6.4 Heater Break Alarm

Heater Break Alarm is a microprocessor based circuit to diagnose partial or total load failure and short circuit on SCR and fuses failure.

- discrimination better than $20 \%$;
- latching alarm plus reset;
- relay output 0.5 A at 125 VAC .


Minimum current 3A. If load current is below this value make two turns or more around current transformer. H.B. circuit also diagnose fuse failure.
H.B. circuit reads load current via a current transformer 25-50/0.05 or 100/0.05 depending on thyristor size.

### 6.4.1 Heater Break Alarm indication

| LED | STATUS | DESCRI PTI ON |
| :---: | :---: | :---: |
| SC | 0 | SCR OK |
|  | $\bullet$ | SCR short circuit |
| HB | 0 | Laod OK |
|  | $\bullet$ | Load Fault |

: LED off
: LED on

The thyristor unit is supplied with a normally closed (N/C) contact.


In alarm condition and without auxiliary voltage the contact is closed (relay coil not energized). In normal condition (no alarm) the contact is open (relay coil energized).

### 6.4.2 Reset

To reset Heater Break Alarm open RESET contact on terminal 3-4.

### 6.4.3 HB alarm contact



Warning: this procedure can be done just by specialized personnel.

The contact of the H.B. Relay is available on auxiliary terminals.

| Terminal | Descriprion |
| :---: | :---: |
| 10 | Common relay HB alarm |
| 11 | NO/NC HB relay alarm |

To change relay status remove plastic cover and configure jumpers as represented below:

| STATUS | RELE STATUS | MAIN PCB <br> $\mathbf{J 1 9}$ |
| :---: | :---: | :---: |
| IN Alarm | Close |  |
| Circuit not <br> powered | Close | C B A <br> (std) |
| OK | Open |  |
| IN Alarm | Open |  |
| Circuit not <br> powered | Open | C B A |
| OK | Close |  |

## Main PCB



### 6.4.4 Calibration

This procedure it's necessary to give set point to Heater Break. CD3000M reads the load current many times and when the value is the same for three times takes it as set point.

Calibration procedure:

- verify that connections are correct;
- supply the thyristor unit;
- push "CAL" button on front of CD3000M unit, or supply with 24 Vdc terminals 1-2 or send command via RS485;
- the thyristor unit goes in conduction state to measure load current;
- all LEDS are ON, this means that calibration procedure is active;
- after one minute LEDS for H.B. and S/C switch off (calibration procedure is done);
- the thyristor unit is ready to work.



### 6.4.5 Digital input Command



### 6.4.6 RS485 Command



If load current decreases for partial or total load failure (sensitivity $20 \%$ standard adjustable via RS485) the yellow LED becomes ON and alarm relay changes status.
If CD3000M is still in conduction with no input signal (LED green OFF) it means that there is a short circuit on thyristors and red LED (SC) becomes ON.


The diagnostic is active only when the switching period is longer than 60ms (3 main voltage cycles).

If the load has been changed calibration procedure must be done again.

### 6.5 Delay triggering option



Warning: this procedure can be done just by specialized personnel.


It's used to switch ON-OFF primary of transformer coupled with resistive load on secondary. It's used to prevent inrush surge current when zero voltage switching is used and to avoid fuse blowing. Every time that auxiliary voltage supply of PCB board is switched ON, the unit starts in phase angle for 1 sec., after witch it switches OFF when the supply waveform is negative and starts again when is positive, giving a delay on triggering signal on first halt positive cycle. If circuit board is maintained under voltage phase angle start is not used.

To enable the delay triggering option, remove the plastic cover and configure the link jumper as below represented:

| Delay | Front PCB |
| :---: | :---: |
| Triggering | J 1 |
| Enabled | $\square \mathrm{A}$ |
|  | $\square \mathrm{B}$ |
| Disabled | $\square \mathrm{C}$ |
| A |  |
|  | $\square \mathrm{C}$ |
|  | JUMPER |

## Front PCB



## 7. Thiristor firing mode



### 7.1 Zero Crossing (ZC)

ZC firing mode is used with Logic Output from temperature controllers and the Thyristor operates like a contactor. The Cycle time is performed by temperature controller. ZC minimizes interferences because the Thyristor unit switches ON-OFF at zero voltage.

### 7.2 Single Cycle (SC)

It's the fastest zero crossing switching method in respect to the power demand from a temperature controller or an external signal. At $50 \%$ input signal is one cycle ON and one cycle OFF. At $75 \%$ is 3 cycles ONone cycle OFF. If power demand is $76 \%$ the unit performs like for $75 \%$ but every time that switches ON the microprocessor divides $76 / 75$ and memorizes the ratio and when the sum of rest is one the unit deliveries one cycle more to the load. With this firing is necessary to have analog input.

### 7.3 Burst Firing (BF)

This firing performed in Digital mode in our Thyristor unit gives a lot of advantages because switches Thyristor at zero voltage crossing without EMC interferences. Analog input is necessary for BF and can be decided how many complete cycles we want at $50 \%$ of power demand. This value can be implemented from 1 to 255 complete cycles doing the firing less or more fast. When 1 is setted the firing name becomes Single Cycle (see above).

### 7.4 Soft Start + Burst Firing ( $\mathrm{S}+\mathrm{BF}$ )

This is an additional feature to Burst Firing. The unit start in phase angle mode with a ramp starting from zero up to full voltage in a presetted and Adjustable time. After which the rest of ON period will be at full conduction. This firing $\mathrm{S}+\mathrm{BF}$ is used to switch ON small inductive loads to avoid inrush surge current and to reduce at minimum electrical interferences.


### 7.5 Delay Triggering+Burst Firing (DT + BF)

It's used to switch ON-OFF primary of transformer coupled with resistive load on secondary. It's used to prevent inrush surge current when zero voltage switching is used and to avoid fuse blowing. Every time that auxiliary voltage supply of PCB board is switched ON, the unit starts in phase angle for 1 sec., after witch it switches OFF when the supply waveform is negative and starts again when is positive, giving a delay on triggering signal on first halt positive cycle. If circuit board is maintained under voltage phase angle start is not used.

### 7.6 Phase Angle ( PA)

With Phase Angle is possible to control the power to the load allowing to Thyristor to be in conduction for a variable part of the voltage supply halt cycle. The load power can be adjusted from 0 to $100 \%$ as a function of analog input signal, normally delivered by temperature controller or by potentiometer. Normal it's used with inductive loads. The only disadvantage with phase angle is the generation of interferences that can be reduced with filters.

### 7.7 Configurator

To configure CD3000M unit, you can download the free software and the Configurator Manual from our web site www.cdautomation.com.


To configure the unit you can use the standard communication on terminals 7-8 or use a programming cable.

To connect the programming cable to the thyristor unit, remove cover as in picture


Once removed the cover, put a side of cable in prog connector(K10) and the other side in the PC RS232(9PIN) serial port.


## 8. Fuse and fuseholder for UL certification units

### 8.1 Fuse and Fuse Code

CD3000M unit must be protected by fuses against short circuit selecting the proper $1^{2} t$ that must be lower than thyristor one. The same caution must be taken if Circuit Breaker is used. Remember that is very difficult to protect the thyristor if this choise is done.


## WARNI NG!! USE SEMI CONDUCTOR FUSES ONLY WITH proper $I^{\mathbf{2}} \mathbf{t}$

| Sizes | Bussmann Div - Cooper (UK) Ltd ( 200 KARMS Symmetrical A.I.C.) |  |  |  | Ferraz Shawmut SA ( 200 kA $_{\text {RMS }}$ Symmetrical A.I.C.) |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | Fuse Mod. No. / modéle fusible | Current ( $\mathrm{A}_{\mathrm{RMS}}$ ) | $\begin{gathered} 1^{2} t \\ \left(A^{2} \mathrm{sec}\right) \end{gathered}$ | V ac | Fuse Mod. No. / modéle fusible | Current (ARMS) | $\begin{array}{c\|} 1^{2} \mathbf{t} \\ \left(A^{2} \sec \right) \end{array}$ | Vac |
| 15A | FWC 16A10F | 16 | 150 | 600 | 660 Grb 10-16 | 16 | 145 | 660 |
| 25A | FWC 32A10F | 32 | 600 | 600 | 660 Grb 10-32 | 32 | 740 | 660 |
| 35A | FWP 40A14F | 40 | 980 | 700 | CP URC 14×51/40 | 40 | 700 | 660 |
| 45A | FWP 50A14F | 50 | 1800 | 700 | CP URC $14 \times 51 / 50$ | 50 | 1500 | 660 |
| 60A | FWP 80A22F | 80 | 5100 | 700 | CP URD $22 \times 58 / 80$ | 80 | 3800 | 660 |
| 90A | N.A. | -- | -- | -- | $\begin{gathered} \text { CP URQ } \\ 27 \times 60 / 125 \\ \hline \end{gathered}$ | 125 | 6970 | 660 |
| 110A | N.A. | -- | -- | -- | $\begin{gathered} \text { CP URQ } \\ 27 \times 60 / 160 \\ \hline \end{gathered}$ | 160 | 15000 | 660 |



High speed fuses are only used for the thyristor protection and can not be used to protect the installation.


The user installation must be protect by electromagnetic circuit breaker or by fuse isolator.


The warranty of thyristor is null if no proper fuses are used. See tab above.

### 8.2 FuseHolder size



35-45A


## 9. Fuse and fuseholder for $C E$ mark unit ( $\in$

### 9.1 Fuse and Fuse Code

The thyristor unit must be protected by fuses against short circuit selecting the proper $1^{2} t$ that must be lower than thyristor one. The same caution must be taken if Circuit Breaker is used. Remember that is very difficult to protect the thyristor if this choise is done.


WARNI NG!! USE SEMI CONDUCTOR FUSES ONLY WITH proper $\mathbf{I}^{\mathbf{2}} \mathbf{t}$

| Sizes | $\begin{gathered} \left.I^{2} \text { T ( max }\right) \\ \left(A^{2} \text { sec. }\right) \end{gathered}$ | Size and current | Fuse and Fuseholder Code | Fuse Code |
| :---: | :---: | :---: | :---: | :---: |
| 15 | 600 | 10,3X38 / 16A | FFH1038/16A | FU1038/16A |
| 25 | 600 | 10,3X38 / 32A | FFH1038/32A | FU1038/32A |
| 35 | 780 | 14X15 / 40A | FFH1451/40A | FU1451/40A |
| 45 | 1500 | 14X15 / 50A | FFH1451/50A | FU1451/50A |
| 60 | 3800 | 22X58 / 80A | FFH2258/80A | FU2258/80A |
| 90 | 6970 | 22X58 / 125A | FFH2258/125A | FU2258/125A |
| 110 | 11000 | 27x60 / 160A | FFHPSI27/160A | FFHPSI27/160A |



High speed fuses are only used for the thyristor protection and can not be used to protect the installation.


The user installation must be protect by electromagnetic circuit breaker or by fuse isolator.


The warranty of thyristor is null if no proper fuses are used. See tab above.

### 9.2 FuseHolder size



35-45A


60-90A


## 10.Modbus communication



The CD3000M is equipped with two-wire RS485-compatible serial communications, by which means communication may occur between the Controller and a master device (e.g. a computer or terminal).

### 10.1 Physical requirements

### 10.1.1 Character Transmission

Data format is fixed to be one start bit, eight data bits, one stop bit, baud rate 9600 and the parity none.

### 10.2 ModBus RTU protocol

The standard RS485 Communications uses the industry standard MODBUS RTU protocol. The following restrictions are imposed:


- Baud rates is fixed to 9600 Baud only.
- Support for multi-parameter Write operations is limited to support of the MultiWord Write Function (Number 16) but it permits the writing of only one parameter per message.

The following MODBUS functions are supported:

| Function | Function Number |
| :--- | :---: |
| Read Holding Registers (Read n Word) | 03 |
| Preset Multiple Registers (Write n Word) | 16 |

The Controller will identify itself in response to a Read Holding Registers message which enquires the values of word parameters 121 and 122 (see Table 4-2).
MODBUS Function 17 (Report Slave ID) is not supported.

### 10.2.1Message Formats

The first character of every message is the Controller address, in the range 1-255 and 0 for broadcast messages.
The second character is always the Function Number.
The contents of the remainder of the message depends upon this Function Number. In most cases the Controller is required to reply to the message by echoing the address and Function Number.


Broadcast messages are supported at address 0 (to which the CD3000M responds by taking some action without sending back any reply).

Data is transmitted as eight-bit binary bytes with one start bit, one stop bit and parity checking set to none. A message is terminated simply by a delay of more than three character lengths at the Baud rate used(in this case 9600 baud); any character received after such a delay is considered to be the potential address at the start of a new message.

Since only the RTU form of the protocol is supported, each message is followed by a two-byte CRC 16 (a 16-bit cyclic redundancy checksum).
This checksum is calculated in accordance with a formula which involves recursive division of the data by a polynomial, with the input to each division being the remainder of the results of the previous division.

The dividing polynomial is
$2^{16}+2^{15}+2^{2}+1($ Hex 18005)
but this is modified in two ways:

- because the bit order is reversed, the binary pattern is also reversed, making the most significant bit (MSB) the right-most bit;
- because only the remainder is of interest, the right-most (most significant) bit can be discarded.

Thus, the polynomial has the value Hex A001.

### 10.2.2 Bit's order

Normal bit order


## Reversed bit order

Least significant bit
 Most significant bit


## N.B.: Reversed order apples, so CRC16 return Reversed bit order



### 10.2.3 C Language CRC 16 Example

```
static short CRC16 (unsigned char *p_first,unsigned char *p_last)
{
    unsigned int crc=0xffff;
    short j;
    for (;p_first<=p_last; p_first++)
    {
    crc ^ = *p_first;
    for(j=8;j>0;j--)
    {
    if(crc & 0x0001)
        {
        crc = crc >> 1;
        crc ^= 0xA001;
        }
    else
        {
        crC = crc >> 1;
        }
    }
    }
return (crc);
}
```


### 10.2.4 Read Holding Registers (Read $\mathbf{n}$ Words) - Function 03

The message sent to the Controller to obtain the value of one or more registers comprises the following eight bytes:

| Addr. unit | Func. | Address <br> $\mathbf{1}^{\circ}$ word |  | $\mathbf{N}^{\circ}$ of Word |  | CRC 16 |  |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
|  | 3 <br> 3 Hex | HI | LO | HI | LO | HI | LO |

The normal reply will echo the first two characters of the message received followed by a singlebyte data byte count (which will not include itself or the CRC).
For this message, the count value equals the number of parameter values read multiplied by two. Following the byte count, the specified number of parameter values are transmitted, followed by the CRC16 bytes:

| Addr. unit | Func. | Cont. | $\mathbf{1}^{\circ}$ Value |  |  | Last Value |  | CRC 16 |  |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
|  | 3 <br> 3 Hex |  | HI | LO |  | HI | LO | HI | LO |

### 10.2.5 Preset Multiple Registers (Write n Words) - Function 16

This is an eleven-byte message. only one parameter may be written for each received message. The usual pre-amble is followed by the address of the parameter to be written, a two-byte word count (always set to 1 ), a single-byte byte count (always set to 2 ), the value to be written and the CRC16 bytes:

| Addr. unit | Func. | Addr of <br> $\mathbf{1}^{\circ}$ Word |  | $\mathbf{N}^{\circ}$ of Word |  | Cont. |  | Valore |  |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
|  | 16 <br> 10 Hex | HI | LO | 0 | 1 | 2 | HI | LO | HI |

The Controller normally responds with the following eight-bit reply:

| Addr. unit | Func. | $\mathbf{N}^{\circ}$ of Word |  | $\mathbf{N}^{\circ}$ Word |  | CRC 16 |  |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
|  | 16 <br> 10 Hex | HI | LO | 0 | 1 | HI | LO |

### 10.2.6 Error and Exception Responses

If a received message contains a corrupted character (parity check failure, framing error etc.) or if the CRC16 check fails, or if the received message is otherwise syntactically flawed (e.g. byte count or word count is incorrect), the thyristor will ignore that message.

If the received message is syntactically correct but nonetheless contains an illegal value, the thyristor will send a five-byte exception response as follows:

| Addr. unit | Func. | N.Exception | CRC 16 |  |
| :--- | :--- | :--- | :--- | :--- |
|  |  |  | HI | LO |

The Function Number byte contains the function number contained in the message which caused the error, with its top bit set (i.e. Function 3 becomes $0 \times 83$ ) and the Exception Number is on of the following codes:

| Code | Name | Cause |
| :--- | :--- | :--- |
| 1 | ILLEGAL FUNCTION | Function number out of range |
| 2 | ILLEGAL DATA ADDRES | Parameter ID out of range or not supported |
| 3 | ILLEGAL DATA VALUE | Attempt to write invalid data/required action not <br> executed |

NOTE: Writing a parameter value equal to its current value is a valid transaction; this will not cause an error response.

### 10.3 Word parameters

| Parameter | N. | Notes |
| :--- | :--- | :--- |
| Heater nominal current | 1 | Read only |
| Set-point HB | 2 | Read / write |
| Status Table (shown in Tab 2.1.2) | 3 | Read only |
| Comand Table (shown in Tab 2.1.3) | 4 | Read /write |
| Output Power (0 - FFH) | 5 | Read - (Write if BIT1in Command table i = 1) <br> $(0->0 \%-$ FF->100\%) |
| Power Adjust (0 - FFH) | 6 | Read -- (Write if BIT1in Command table i = <br> $1)$ <br> $(0->0 \% ~-~ F F->100 \%) * ~$ |

### 10.3.1 Heater nominal current

Parameter 1
Operation: Read

## Meaning:

It correspond at one value in points (0-255,0-FF Hex).
It represents average current value flowing into thyristors.
Value depends on current transformer ratio that is different from one size to the other one (see below table)

| Nominal current <br> $\mathbf{( A )}$ | Zero (0, O Hex) <br> $(\mathrm{A})$ | Max (255, ff Hex) <br> $\mathbf{( A )}$ |
| :---: | :---: | :---: |
| 3,5 | 0 | 3,5 |
| 15 | 0 | 25 |
| 25 | 0 | 25 |
| 35 | 0 | 50 |
| 45 | 0 | 50 |
| 60 | 0 | 100 |
| 90 | 0 | 100 |
| 110 | 0 | 100 |

Operations: Read/Write

## Meaning:

It correspond at one value in points (0-255, o-FF Hex). It's the set of current value below which HB alarm occurs.
This value is the load current minus \% value of parameter 124 H . This value depend on nominal current of transformer that change in function of thyristor nominal current as described in below tab.

| Nominal current <br> (A) | Zero (0, 0 Hex) <br> $\mathbf{( A )}$ | Max (255, ff Hex) <br> $\mathbf{( A )}$ |
| :---: | :---: | :---: |
| 3,5 | 0 | 3,5 |
| 15 | 0 | 25 |
| 25 | 0 | 25 |
| 35 | 0 | 50 |
| 45 | 0 | 50 |
| 60 | 0 | 100 |
| 90 | 0 | 100 |
| 110 | 0 | 100 |

### 10.3.3 Status Table <br> Parameter 3 <br> Operations: Read

## Meaning:

It's a tab in bit that represent the "Status" of thyristor unit

### 10.3.4 Comand Table

Parameter 4
Operations: Read/Write

## Meaning:

It's a tab in bit for remote commands via RS485 (see tab)

### 10.3.5 Output Power

## Parameter 5

Command from controller
Operations: Read

## Meaning:

It rapresent a value in points ( $0-255,0-\mathrm{FF} \mathrm{Hex}$ ) and it's the power demand in $\%$ of controller.
Example:

| $0 \%$ | $=0$ | $0(\mathrm{Hex})$ |
| :--- | :--- | :--- |
| $50 \%$ | $=128$ | 80 (Hex) |
| $100 \%$ | $=255$ | FF (Hex) |

Command via RS485
Operations : Read/Write

## Meaning:

It's a value in points (0-255, 0-FF Hex)
It's power set point setted in thirst buffer
Example:

| $0 \%$ | $=0$ | $0($ Hex $)$ |
| :--- | :--- | :--- |
| $50 \%$ | $=128$ | 80 (Hex) |
| $100 \%$ | $=255$ | FF (Hex) |

### 10.3.6 Power adjust

Parameter 6
Operations: Read/Write

## Meaning:

Its' a value in points (0-255, 0-FF Hex)
Its' a scaling factor of power demand
Example 1:

$$
\begin{array}{ll}
0 \% & =0 \\
50 \% & =128 \\
100 \% & =255
\end{array}
$$

Example 2:

- Output Power : 100 Power Limit : 100 -> Power real : 100
- Output Power : 100 Power Limit: 50 -> Power real : 50
- Output Power : 80 Power Limit : 50 -> Power real : 40



### 10.3.7 Status Table

| Bit | Meaning | Notes |
| :--- | :--- | :--- |
| 0 | Short circuit on SCR | Read only |
| 1 | Load Failure | Read only |
| 2 | On-Off | Read only |
| 3 | HB Calibration in progress | Read only $0=$ Normal $-1=$ Calibration |

### 10.3.7.1 Short circuit on SCR

## Meaning:

Its' a status but that represents the short circuit on thyristor
$0 \quad=\mathrm{OK}$
1 = Short circuit
10.3.7.2 Load Failure

Operations: Read

## Meaning:

It's a bit that represent partial or total load failure.
$0 \quad=$ OK
1 = Load failure

### 10.3.7.3 On-Off

Operations: Read

## Meaning:

It's a bit that represent when input signal is ON
$0 \quad=$ Input signal OFF
$1 \quad=$ Input signal ON

### 10.3.7.4 HB Calibration in progress

## Operations: Read

## Meaning:

IT'S A BIT STATUS THAT REPRESENT "CALIBRATION IN PROGRESS"
$0 \quad=$ No calibration
$1=$ Calibration in progress

### 10.3.8 Command Table

| Bit | Meaning | Notes |  |
| :--- | :--- | :--- | :--- |
| 0 | HB Calibration | Read /write 0=Off $-\quad$ 1=ACTVATE Calibration <br> $($ normal mode set to 0) |  |
| 1 | Firing command | Read /write 0=from terminal - | $1=$ from RS485 |
| 2 | On-Off | Read /write 0=Off - | $1=$ On |
| 3 | RESET HB | Read /write 0=Off - <br> $($ normal mode set to 0) | $1=$ RESET |

N.B.: When unit is switch off all command parameter are set to 0

### 10.3.8.1 HB Calibration

Operations: Read / Write

## Meaning:

It's a bit that starts the HB calibration procedure
When this bit is zero start the calibration procedure and reset itself automatically at the end.

### 10.3.8.2 Firing command

Bit 1
Operations: Read / Write

## Meaning:

It's a command bit used to switch from analog external command to command via RS485
$0 \quad=$ Command of analog input
$1=$ Command of RS485 input

### 10.3.8.3 On-Off

Operations: Read / Write

## Meaning:

Its' an enable bit to switch ON-OFF the power.
$0 \quad=$ Power disabled
1 = Power enabled

### 10.3.8.4 HB RESET

Operations: Read / Write

## Meaning:

It's a command bit to reset HB alarm.
This parameter has to be at 0 to have the alarm working properly
$0 \quad=$ Reset disabled
$1=$ Reset enabled

### 10.4 Thyristor unit Configuration

| Parameter | N. | Notes |
| :--- | :--- | :--- |
| Password | 123 | Write |
| Delay trigger | 124 L | Read /write |
| \% HB | 124 H | Read /write |
| Firing type | 125 L | Read /write |
| Soft start time | 125 H | Read /write |
| $\mathrm{N}^{\circ}$ burst | 126 L | Read /write |
| Delay time HB | 126 H | Read /write |
| Max power for SSR Input | 127 L | Read /write |
| Cycle time | 127 H | Read /write |
| $\mathrm{N}^{\circ}$ of half period for Delayed triggering | 128 L | Read /write (Mantenere a 1) |
|  | 128 H | Read /write |

### 10.4.1 Password

Parameter 123
Operations: Write

## Meaning:

If properly setted give the access to configuration

### 10.4.2 Delay triggering

Parameter 124L
Operations: Read/Write

## Meaning:

It's correspond to a value in points (0-50, 0-32 Hex)
Each step is $0,1 \mathrm{msec}$. Range is $0-5 \mathrm{msec}$.
This parameter is the delay of firig in first half period with respect zero voltage crossing.

## 10.4 .3 \% HB

Parameter 124H
Operations: Read/Write

## Meaning:

It's correspond to a value in point (0-255, 0-ff Hex)
This parameter is the value in \% that decrease the load current to establish the HB current set point

Example:

| Load current | $=10 \mathrm{~A}$ |  |
| :--- | :--- | :--- |
| Parameter 124 H | $=20 \%$ | 51 Dec |
| Parameter 2 will be setted at 8 A |  |  | Hex

### 10.4.4 Firing type

Parameter 125L
Operations: Read/Write

## Meaning:

Selection table of firing modes.

| Value |  | Type | Option |
| :--- | :--- | :--- | :--- |
| H | L |  |  |
| 0 | 1 | Zero Crossing | - |
| 0 | 2 | Single Cycle | - |
| 0 | 3 | Burst | - |
| 1 | 1 | Zero Crossing | Soft Start |
| 1 | 2 | Single Cycle | - |
| 1 | 3 | Burst | Soft Start |
| 2 | 1 | Zero Crossino | Delay trigger |
| 2 | 2 | Single Cycle |  |
| 2 | 3 | Burst | Delay triggering |
| 2 | 4 | Phase angle | Soft start |

### 10.4.5 Soft start time

Parameter 125H
Operations: Read/Write


## Meaning :

It's correspond to a value in points ( $0-255,0-\mathrm{FFHex}$ ).
Each step is 5 msec .
The unit start in phase angle mode with a ramp starting from zero up to full voltage in a presetted and Adjustable time. The time is setted by this parameter.

Value of this parameter must be less than cycle time.
For burst firing:
Value of this parameter must be less than:
$50 \mathrm{~Hz}->20 \mathrm{msec} \quad x$ Number of cycles (Parameter 126L).
$60 \mathrm{~Hz}->16,6 \mathrm{msec} \quad x$ Number of cycles (Parameter 126L).

### 10.4.6 ${ }^{\circ}$ burst

Parameter 126L
Operations: Read/Write

## Meaning:

It's a value in point ( $0-255,0-$ FF Hex).
In burst firing mode it rapresents the number of cycles at 50\% power demand

### 10.4.7 Delay time HB

Parameter 126H
Operations: Read/Write

## Meaning:

It's a value in point ( $0-255,0-F F$ Hex).
Each step is 50 msec .
It represent a delay to have HB alarm active
When is used soft start this time must be longer than soft start time.
Par126H x 50msec > Par125H x 5msec
When zero crossing firing is used must be less than cycle time
Par126H x 50msec > Par127H x 50msec

### 10.4.8 Max power for SSR I nput

Parameter 127L
Operations: Read/Write

## Meaning:

It's a value in points ( $0-255,0-F F H e x)$.
When SSR input is used it represent the value of the power (\%) when is in ON status.
It's the power \% when firing command is given on RS485 (1).
Example:

| $0 \%$ | $=0$ | $0(\mathrm{Hex})$ |
| :--- | :--- | :--- |
| $50 \%$ | $=128$ | 80 (Hex) |
| $100 \%$ | $=255$ | FF (Hex) |

10.4.9 Cycle time

Parameter 127H
Operations: Read/Write

## Meaning:

It's a value in points ( $0-255,0-F F H e x)$.
Each step is 50 msec .


When single cycle (SC) and burst firing (BF) is used must be setted at 240 (FO Hex)
When SSR input is used set at 240 (FO Hex)
When is used zero crossing (ZC) represents the cycle time (ON time + OFF time, default 60(3C Hex) )
10.4.10 Number of half periods for DT firing

Parameter 128L Operations: Read/Write

## Meaning:

Must be setted at 1.

### 10.5 Address configuration



To Configure communication address remove cover and set the dip-switch as below specified.

### 10.5.1 Address table

| ID | $\mathbf{8}$ | $\mathbf{7}$ | $\mathbf{6}$ | $\mathbf{5}$ | $\mathbf{4}$ | $\mathbf{3}$ | $\mathbf{2}$ | $\mathbf{1}$ |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| 1 | - | - | - | - | - | - | - | X |
| 2 | - | - | - | - | - | - | X | - |
| 3 | - | - | - | - | - | - | X | X |
| 4 | - | - | - | - | - | X | - | - |
| 5 | - | - | - | - | - | X | - | X |
| 6 | - | - | - | - | - | X | X | - |
| 7 | - | - | - | - | - | X | X | X |
| 8 | - | - | - | - | X | - | - | - |
| 9 | - | - | - | - | X | - | - | X |
| 10 | - | - | - | - | X | - | X | - |
| 11 | - | - | - | - | X | - | X | X |
| 12 | - | - | - | - | X | X | - | - |
| 13 | - | - | - | - | X | X | - | X |
| 14 | - | - | - | - | X | X | X | - |
| 15 | - | - | - | - | X | X | X | X |
| 16 | - | - | - | X | - | - | - | - |
| 17 | - | - | - | X | - | - | - | X |
| 18 | - | - | - | X | - | - | X | - |
| 19 | - | - | - | X | - | - | X | X |
| 20 | - | - | - | X | - | X | - | - |
| 21 | - | - | - | X | - | X | - | X |
| 22 | - | - | - | X | - | X | X | - |
| 23 | - | - | - | X | - | X | X | X |
| 24 | - | - | - | X | X | - | - | - |
| 25 | - | - | - | X | X | - | - | X |


| $\mathbf{I D}$ | $\mathbf{8}$ | $\mathbf{7}$ | $\mathbf{6}$ | $\mathbf{5}$ | $\mathbf{4}$ | $\mathbf{3}$ | $\mathbf{2}$ | $\mathbf{1}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 26 | - | - | - | X | X | - | X | - |
| 27 | - | - | - | X | X | - | X | X |
| 28 | - | - | - | X | X | X | - | - |
| 29 | - | - | - | X | X | X | - | X |
| 30 | - | - | - | X | X | X | X | - |
| 31 | - | - | - | X | X | X | X | X |
| 32 | - | - | X | - | - | - | - | - |
| 33 | - | - | X | - | - | - | - | X |
| 34 | - | - | X | - | - | - | X | - |
| 35 | - | - | X | - | - | - | X | X |
| 36 | - | - | X | - | - | X | - | - |
| 37 | - | - | X | - | - | X | - | X |
| 38 | - | - | X | - | - | X | X | - |
| 39 | - | - | X | - | - | X | X | X |
| 40 | - | - | X | - | X | - | - | - |
| 41 | - | - | X | - | X | - | - | X |
| 42 | - | - | X | - | X | - | X | - |
| 43 | - | - | X | - | X | - | X | X |
| 44 | - | - | X | - | X | X | - | - |
| 45 | - | - | X | - | X | X | - | X |
| 46 | - | - | X | - | X | X | X | - |
| 47 | - | - | X | - | X | X | X | X |
| 48 | - | - | X | X | - | - | - | - |
| 49 | - | - | X | X | - | - | - | X |
| 50 | - | - | X | X | - | - | X | - |


| ID | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 51 | - | - | X | X | - | - | X | X |
| 52 | - | - | X | X | - | X | - | - |
| 53 | - | - | X | X | - | X | - | X |
| 54 | - | - | X | X | - | X | X | - |
| 55 | - | - | X | X | - | X | X | X |
| 56 | - | - | X | X | X | - | - | - |
| 57 | - | - | X | X | X | - | - | X |
| 58 | - | - | X | X | X | - | X | - |
| 59 | - | - | X | X | X | - | X | X |
| 60 | - | - | X | X | X | X | - | - |
| 61 | - | - | X | X | X | X | - | X |
| 62 | - | - | X | X | X | X | X | - |
| 63 | - | - | X | X | X | X | X | X |
| 64 | - | X | - | - | - | - | - | - |
| 65 | - | X | - | - | - | - | - | X |
| 66 | - | X | - | - | - | - | X | - |
| 67 | - | X | - | - | - | - | X | X |
| 68 | - | X | - | - | - | X | - | - |
| 69 | - | X | - | - | - | X | - | X |
| 70 | - | X | - | - | - | X | X | - |
| 71 | - | X | - | - | - | X | X | X |
| 72 | - | X | - | - | X | - | - | - |
| 73 | - | X | - | - | X | - | - | X |
| 74 | - | X | - | - | X | - | X | - |
| 75 | - | X | - | - | X | - | X | X |
| 76 | - | X | - | - | X | X | - | - |
| 77 | - | X | - | - | X | X | - | X |
| 78 | - | X | - | - | X | X | X | - |
| 79 | - | X | - | - | X | X | X | X |
| 80 | - | X | - | X | - | - | - | - |
| 81 | - | X | - | X | - | - | - | X |
| 82 | - | X | - | X | - | - | X | - |
| 83 | - | X | - | X | - | - | X | X |
| 84 | - | X | - | X | - | X | - | - |
| 85 | - | X | - | X | - | X | - | X |
| 86 | - | X | - | X | - | X | X | - |
| 87 | - | X | - | X | - | X | X | X |
| 88 | - | X | - | X | X | - | - | - |
| 89 | - | X | - | X | X | - | - | X |
| 90 | - | X | - | X | X | - | X | - |
| 91 | - | X | - | X | X | - | X | X |
| 92 | - | X | - | X | X | X | - | - |
| 93 | - | X | - | X | X | X | - | X |
| 94 | - | X | - | X | X | X | X | - |
| 95 | - | X | - | X | X | X | X | X |
| 96 | - | X | X | - | - | - | - | - |
| 97 | - | X | X | - | - | - | - | X |
| 98 | - | X | X | - | - | - | X | - |
| 99 | - | X | X | - | - | - | X | X |
| 100 | - | X | X | - | - | X | - | - |


| ID | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 101 | - | X | X | - | - | X | - | X |
| 102 | - | X | X | - | - | X | X | - |
| 103 | - | X | X | - | - | X | X | X |
| 104 | - | X | X | - | X | - | - | - |
| 105 | - | X | X | - | X | - | - | X |
| 106 | - | X | X | - | X | - | X | - |
| 107 | - | X | X | - | X | - | X | X |
| 108 | - | X | X | - | X | X | - | - |
| 109 | - | X | X | - | X | X | - | X |
| 110 | - | X | X | - | X | X | X | - |
| 111 | - | X | X | - | X | X | X | X |
| 112 | - | X | X | X | - | - | - | - |
| 113 | - | X | X | X | - | - | - | X |
| 114 | - | X | X | X | - | - | X | - |
| 115 | - | X | X | X | - | - | X | X |
| 116 | - | X | X | X | - | X | - | - |
| 117 | - | X | X | X | - | X | - | X |
| 118 | - | X | X | X | - | X | X | - |
| 119 | - | X | X | X | - | X | X | X |
| 120 | - | X | X | X | X | - | - | - |
| 121 | - | X | X | X | X | - | - | X |
| 122 | - | X | X | X | X | - | X | - |
| 123 | - | X | X | X | X | - | X | X |
| 124 | - | X | X | X | X | X | - | - |
| 125 | - | X | X | X | X | X | - | X |
| 126 | - | X | X | X | X | X | X | - |
| 127 | - | X | X | X | X | X | X | X |
| 128 | X | - | - | - | - | - | - | - |
| 129 | X | - | - | - | - | - | - | X |
| 130 | X | - | - | - | - | - | X | - |
| 131 | X | - | - | - | - | - | X | X |
| 132 | X | - | - | - | - | X | - | - |
| 133 | X | - | - | - | - | X | - | X |
| 134 | X | - | - | - | - | X | X | - |
| 135 | X | - | - | - | - | X | X | X |
| 136 | X | - | - | - | X | - | - | - |
| 137 | X | - | - | - | X | - | - | X |
| 138 | X | - | - | - | X | - | X | - |
| 139 | X | - | - | - | X | - | X | X |
| 140 | X | - | - | - | X | X | - | - |
| 141 | X | - | - | - | X | X | - | X |
| 142 | X | - | - | - | X | X | X | - |
| 143 | X | - | - | - | X | X | X | X |
| 144 | X | - | - | X | - | - | - | - |
| 145 | X | - | - | X | - | - | - | X |
| 146 | X | - | - | X | - | - | X | - |
| 147 | X | - | - | X | - | - | X | X |
| 148 | X | - | - | X | - | X | - | - |
| 149 | X | - | - | X | - | X | - | X |
| 150 | X | - | - | X | - | X | X | - |


| ID | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 151 | X | - | - | X | - | X | X | X |
| 152 | X | - | - | X | X | - | - | - |
| 153 | X | - | - | X | X | - | - | X |
| 154 | X | - | - | X | X | - | X | - |
| 155 | X | - | - | X | X | - | X | X |
| 156 | X | - | - | X | X | X | - | - |
| 157 | X | - | - | X | X | X | - | X |
| 158 | X | - | - | X | X | X | X | - |
| 159 | X | - | - | X | X | X | X | X |
| 160 | X | - | X | - | - | - | - | - |
| 161 | X | - | X | - | - | - | - | X |
| 162 | X | - | X | - | - | - | X | - |
| 163 | X | - | X | - | - | - | X | X |
| 164 | X | - | X | - | - | X | - | - |
| 165 | X | - | X | - | - | X | - | X |
| 166 | X | - | X | - | - | X | X | - |
| 167 | X | - | X | - | - | X | X | X |
| 168 | X | - | X | - | X | - | - | - |
| 169 | X | - | X | - | X | - | - | X |
| 170 | X | - | X | - | X | - | X | - |
| 171 | X | - | X | - | X | - | X | X |
| 172 | X | - | X | - | X | X | - | - |
| 173 | X | - | X | - | X | X | - | X |
| 174 | X | - | X | - | X | X | X | - |
| 175 | X | - | X | - | X | X | X | X |
| 176 | X | - | X | X | - | - | - | - |
| 177 | X | - | X | X | - | - | - | X |
| 178 | X | - | X | X | - | - | X | - |
| 179 | X | - | X | X | - | - | X | X |
| 180 | X | - | X | X | - | X | - | - |
| 181 | X | - | X | X | - | X | - | X |
| 182 | X | - | X | X | - | X | X | - |
| 183 | X | - | X | X | - | X | X | X |
| 184 | X | - | X | X | X | - | - | - |
| 185 | X | - | X | X | X | - | - | X |
| 186 | X | - | X | X | X | - | X | - |
| 187 | X | - | X | X | X | - | X | X |
| 188 | X | - | X | X | X | X | - | - |
| 189 | X | - | X | X | X | X | - | X |
| 190 | X | - | X | X | X | X | X | - |
| 191 | X | - | X | X | X | X | X | X |
| 192 | X | X | - | - | - | - | - | - |
| 193 | X | X | - | - | - | - | - | X |
| 194 | X | X | - | - | - | - | X | - |
| 195 | X | X | - | - | - | - | X | X |
| 196 | X | X | - | - | - | X | - | - |
| 197 | X | X | - | - | - | X | - | X |
| 198 | X | X | - | - | - | X | X | - |
| 199 | X | X | - | - | - | X | X | X |
| 200 | X | X | - | - | X | - | - | - |

$$
\begin{array}{|lll|}
\hline \mathrm{X} & = & \mathrm{ON} \\
- & = & \mathrm{OFF} \\
\hline
\end{array}
$$

| ID | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 201 | X | X | - | - | X | - | - | X |
| 202 | X | X | - | - | X | - | X | - |
| 203 | X | X | - | - | X | - | X | X |
| 204 | X | X | - | - | X | X | - | - |
| 205 | X | X | - | - | X | X | - | X |
| 206 | X | X | - | - | X | X | X | - |
| 207 | X | X | - | - | X | X | X | X |
| 208 | X | X | - | X | - | - | - | - |
| 209 | X | X | - | X | - | - | - | X |
| 210 | X | X | - | X | - | - | X | - |
| 211 | X | X | - | X | - | - | X | X |
| 212 | X | X | - | X | - | X | - | - |
| 213 | X | X | - | X | - | X | - | X |
| 214 | X | X | - | X | - | X | X | - |
| 215 | X | X | - | X | - | X | X | X |
| 216 | X | X | - | X | X | - | - | - |
| 217 | X | X | - | X | X | - | - | X |
| 218 | X | X | - | X | X | - | X | - |
| 219 | X | X | - | X | X | - | X | X |
| 220 | X | X | - | X | X | X | - | - |
| 221 | X | X | - | X | X | X | - | X |
| 222 | X | X | - | X | X | X | X | - |
| 223 | X | X | - | X | X | X | X | X |
| 224 | X | X | X | - | - | - | - | - |
| 225 | X | X | X | - | - | - | - | X |
| 226 | X | X | X | - | - | - | X | - |
| 227 | X | X | X | - | - | - | X | X |
| 228 | X | X | X | - | - | X | - | - |
| 229 | X | X | X | - | - | X | - | X |
| 230 | X | X | X | - | - | X | X | - |
| 231 | X | X | X | - | - | X | X | X |
| 232 | X | X | X | - | X | - | - | - |
| 233 | X | X | X | - | X | - | - | X |
| 234 | X | X | X | - | X | - | X | - |
| 235 | X | X | X | - | X | - | X | X |
| 236 | X | X | X | - | X | X | - | - |
| 237 | X | X | X | - | X | X | - | X |
| 238 | X | X | X | - | X | X | X | - |
| 239 | X | X | X | - | X | X | X | X |
| 240 | X | X | X | X | - | - | - | - |
| 241 | X | X | X | X | - | - | - | X |
| 242 | X | X | X | X | - | - | X | - |
| 243 | X | X | X | X | - | - | X | X |
| 244 | X | X | X | X | - | X | - | - |
| 245 | X | X | X | X | - | X | - | X |
| 246 | X | X | X | X | - | X | X | - |
| 247 | X | X | X | X | - | X | X | X |
| 248 | X | X | X | X | X | - | - | - |
| 249 | X | X | X | X | X | - | - | X |
| 250 | X | X | X | X | X | - | X | - |
| 251 | X | X | X | X | X | - | X | X |
| 252 | X | X | X | X | X | X |  |  |
| 253 | X | X | X | X | X | X |  | X |
| 254 | X | X | X | X | X | X | X |  |
| 255 | X | X | X | X | X | X | X | X |

## 11. Maintenance

### 11.1 Trouble Shooting

Small problems sometimes can be solved locally with the help of the below tab of trouble shooting. If you don't succeed, contact us or your nearest distributor.

| Symptom | I ndication on front unit | Possible reasons of the symptom | Actions |
| :---: | :---: | :---: | :---: |
| Thyristor unit doesn't go in conduction with input signal. | Green LED is always light off. | - No voltage auxiliary power supply to terminals 1-3 (see wiring diagram). | - Give auxiliary voltage supply to terminals 1-3. |
|  | Green LED (PW) light on and green LED (ON) in light off condition. | - No input signal. <br> - Reversed polarities of input signal. <br> - Reset contact in open condition (see wiring diagram). | - Provide to give input signal. Reverse the input signal polarity. <br> - Make link on reset terminals. |
|  | Green LED (PW) in light on condition and green LED (ON) in light on condition. | Fuse failure. Load failure. <br> Load connection interruption. Thyristor faulty and always in open circuit. <br> With HB option the yellow led (HB) in light on condition. | - Substitute the fuse. <br> - Repair the load. <br> - Provide to repair the wiring. <br> - Substitute the faulty thyristor. <br> - Check the load. |
| Load current flows also with no input signal. | Green LED (ON) always in light off condition. | - Short circuit on thyristor. If there is HB circuit the red LED (SC) is light on. | - Substitute the thyristor. Check that load is not in short circuit. |
| Current flows at nominal value but yellow LED (HB) in light on condition. | Yellow HB in light on condition. | - HB circuit not tuned. <br> Current transformers not properly wired (if are external to CD3000). | Push CAL button in front unit to start HB calibration procedure. <br> Control current transformers wiring and Push CAL button in front unit to start HB calibration procedure. |
| Red LED (SC) is lighted also if current is at nominal value. | Red LED in light on condition. | - HB circuit not properly tuned. | Push CAL button in front unit to start HB calibration procedure. |
| Thyristor unit doesn't work properly. |  | Wrong input signal selection. Wrong input signal calibration (out of range). <br> Auxiliary voltage supply out of limits. | - Control input signal setting. Repeat input calibration procedure. <br> Verify the auxiliary voltage supply. |

### 11.2 Repairing procedure

- Phone to us.
- Explain to Service Engineer the problem because sometimes it can be solved with a phone call.
- If this is not possible ship the unit to us or to your distributor.
- Write a fault description and give the name of your personnel to which refer.
- Use a rugged packaging to ship the unit.


### 11.3 Fans

The thyristor unit with forced ventilation uses fans that rotate permanently when the unit is supplied. In case of accidental fan failure, there is an over heating temperature on heatsink. In this case to give protection to thyristor there is a thermal switch properly setted. The function of this switch is to open the input signal until the heatsink temperature falls below the setted value. This means that also with input signal in ON condition the unit is switched OFF and the system can not work at full power. For these reason is important to control periodically the fan status checking that is rotating.

### 11.4 Servicing

In order to have correct cooling, the user must clean the heatsink and the protective grill of fan. The frequence of this servicing depends on environmental pollution.
Check periodically also if the screw for the power cables and safety earth are tightened correctly

### 11.5 Warranty conditions

We gives a 12 months warranty to its products. The warranty is limited to repairing and parts substitution in our factory and does exclude products not properly used and fuses.
Warranty does not includes products with serial numbers deleted. The faulty product should be shipped to us at your cost and our Service will evaluate if product is under warranty terms.
Substituted parts remains our property.

## 12. CD Automation's distributors

For a more precise and rapid service, please contact the distributor nearest to you:

## ITALY

## CABE S.r.I.

Via Ferrara, 15/17
40018 S. Pietro in Casale (BO)
Tel: 0516661345
Fax: 0516661283
Sig. Bergonzoni
info@cabesrl.it
CEAM Control Equip. S.r.I.
Via Val d'Orme, 291
50053 Empoli ( FI )
Tel: 0571924181
Fax: 0571924505
Sig. Campinoti
info@ceamgroup.it

## Vectra Misure S.r.I.

Via Gaidano, 109/17
10137 Torino (TO)
Tel: 0113097003
Fax: 0113098799
Sig. Cochis
vectramisure@libero.it

## Secif S.a.s.

Via Bachelet, 27
35010 Busa di Vigonza (PD)
Tel: 0498934422
Fax: 0498934415
Sig. Ferro
info@secif.com

## Studio Rapaccini S.a.s.

Via del Rivo, 138
05100 Terni (TR)
Tel: 0744305105
Cell: 3356163428
Fax: 0744305110
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Mr. Peter Hallwas

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Mr. Ravi Toshniwal

## CasCade Automation Systems BV

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mailer@cascade-a-s.com

## Teck Instrument AS

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CRA - Mess-, Regel- + Antriebstechnik AG
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Fax: +41552126960
Mr. Chiauzzi
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Fax: +46 22010403
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http://www.la-konsult.se
leif@la-konsult.se

## CONTROLTEMP, SL

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Fax: +34 935744116
info@controltemp.net
http://www.controltemp.net

## Danaher Corporation

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Mr. Andrew Ross
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## Beta Technic Aps

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Fax: +4545662206
Sune Granzow
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Quinta Do Simao en 109 Esgueira
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Fax: +351 234303329
Mr. Carlos Breda

